

Phys 231 Exam 3
March 30, 2018

NAME: Solutions

Student I.D. No. _____

Keep in mind that I must be able to follow your work in order to give you credit. This is especially true when awarding partial credit. A wrong answer with the right methods gets partial credit. If I cannot figure out the methods then no credit even if the answer is correct.

Answers must be justified. An answer by itself receives no credit.

All Units All the Time!

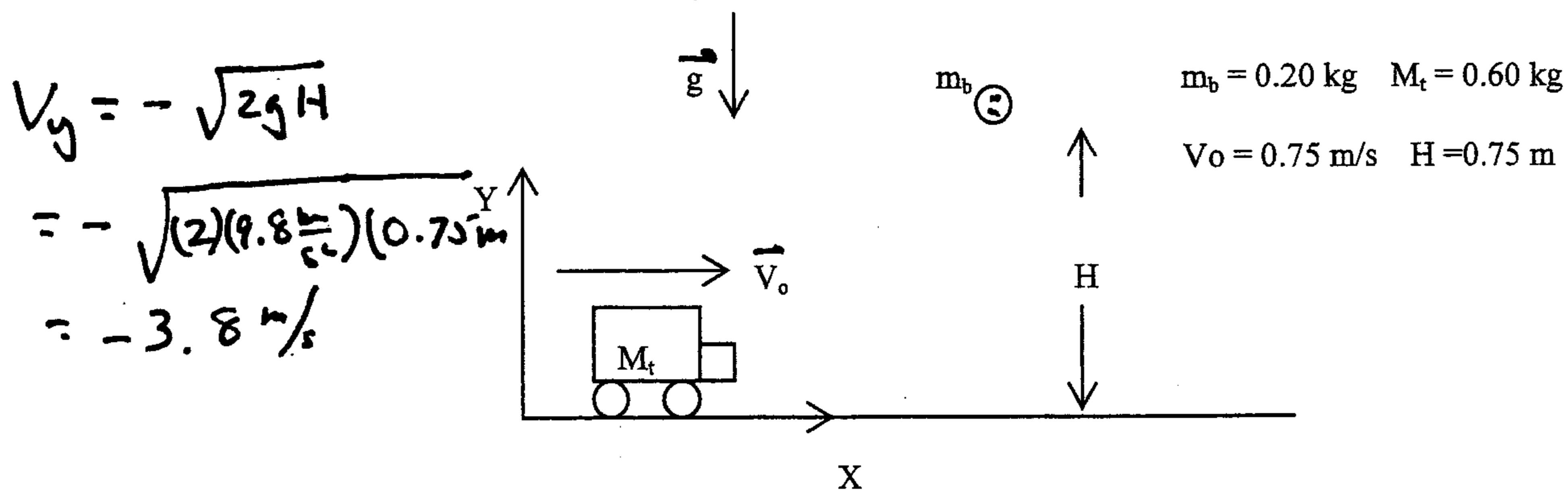
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1) (20 pts) The picture below shows a toy truck moving with constant initial velocity along a rigid surface with no friction. A ball is dropped (zero initial velocity) from a height H and lands in the truck. The ball bounces around a bit and stays in the truck. Both the truck and the ball may be treated as point-like objects.



a) Use the co-ordinate system drawn on the diagram. What is the center of mass velocity (vector) of the system (truck plus ball) just before the collision of the ball and truck?

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$$\vec{V}_{cm} = \frac{M_t \vec{V}_0 + m_b \vec{V}_b}{M_t + m_b}$$

$$= \frac{(0.75 \frac{m}{s})(0.60 \text{ kg}) \hat{i} + (3.8 \frac{m}{s})(0.20 \text{ kg})(-\hat{j})}{0.80 \text{ kg}}$$

$$= (0.56 \hat{i} - 0.95 \hat{j}) \frac{m}{s}$$

b) What is the center of mass velocity (vector) of the system (truck plus ball) after the ball is in the truck and is at rest with respect to the truck?

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$$\vec{V}_{cm} = 0.56 \hat{i} \frac{m}{s}$$

7

c) What is the velocity (vector) of the truck – ball system after the ball lands in the truck?

$$V = 0.56 \frac{\text{m}}{\text{s}} \hat{i}$$

5

d) Remember that momentum is a vector. You must provide justification to your answers to the following questions. A correct answer without the proper justification receives no credit

i) Is the X-component of momentum of the system (ball plus truck) conserved by the collision of the truck and ball?

Yes - no external forces act along the X-axis

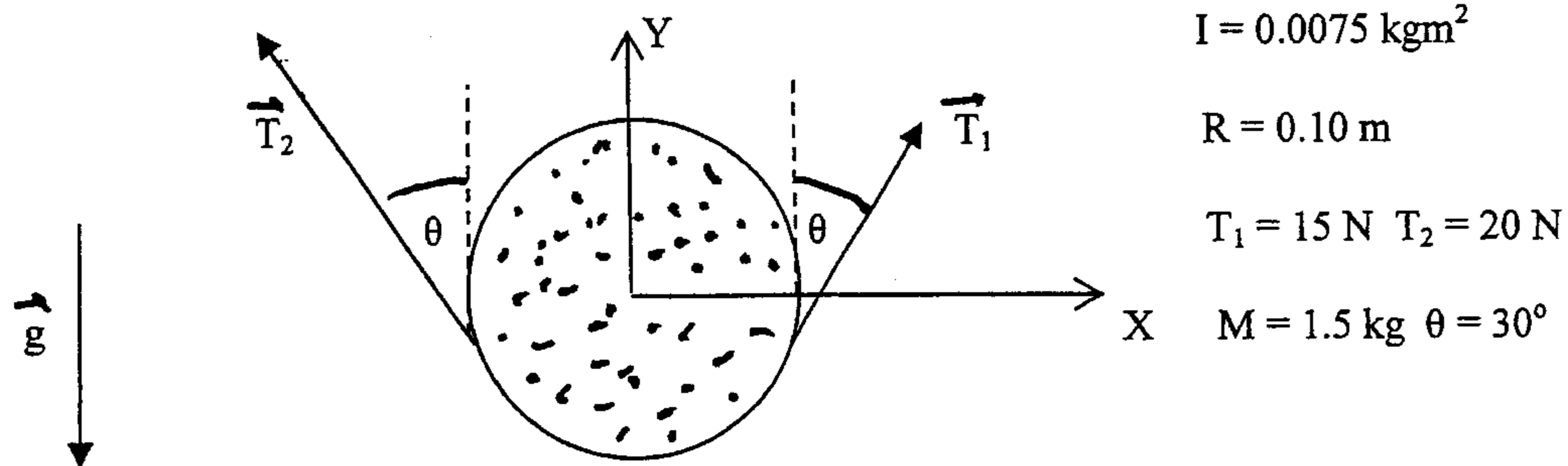
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ii) Is the Y-component of momentum of the system conserved by the collision of the truck and ball?

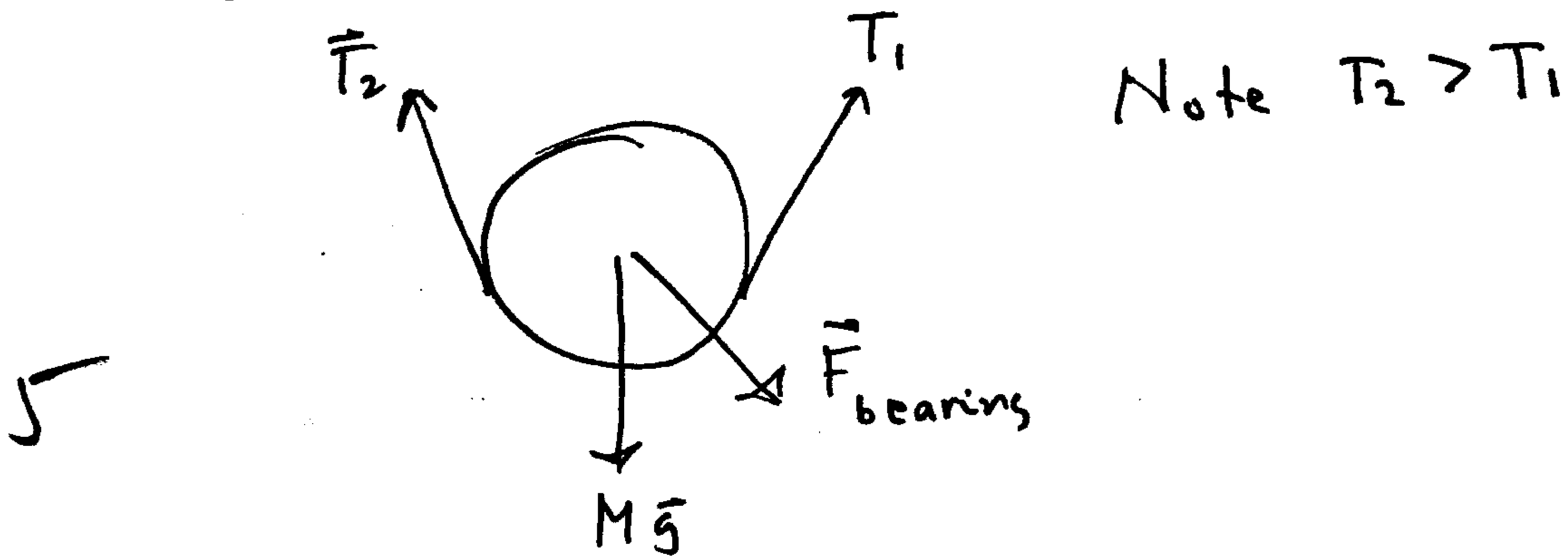
No - $N - mg \neq 0$ during the collision.

There is a net y-component of external force acting during the collision

2) (15 pts) The picture below shows a pulley with a belt wrapped around it with the tensions T in the belt specified. Not drawn is the stationary bearing at the center of the pulley about which the pulley rotates.



a) Draw a force diagram for the pulley.



b) Calculate the net torque (vector - specify direction unambiguously) acting on the pulley. Use the origin (located at the center of the pulley) and co-ordinate system shown.

$$\begin{aligned}
 \tau &= (T_2 - T_1)R \\
 &= (20 - 15) \text{ N} (0.10 \text{ m}) \\
 &= 0.50 \text{ Nm } (\otimes)
 \end{aligned}$$

c) The pulley has an initial angular velocity of zero. After 1.0 minute, how many revolutions has the pulley made?

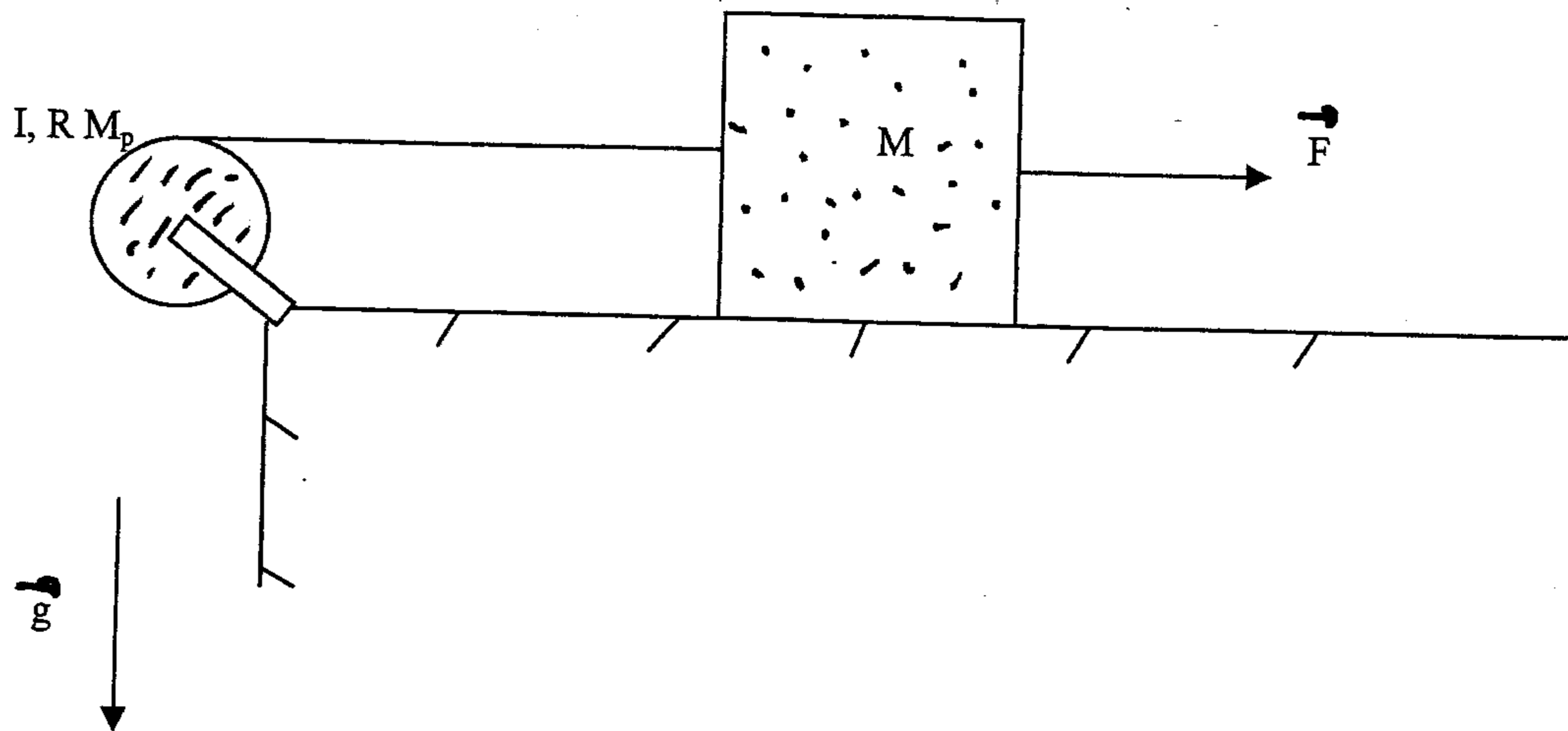
$$\Delta\theta = \frac{1}{2} \alpha t^2 \quad \alpha = \frac{\tau}{I}$$

$$= \left(\frac{1}{2}\right) \left(\frac{0.50 \text{ Nm}}{0.0075 \text{ kg m}^2} \right) (60 \text{ s})^2 \left(\frac{1 \text{ rev}}{2\pi} \right)$$

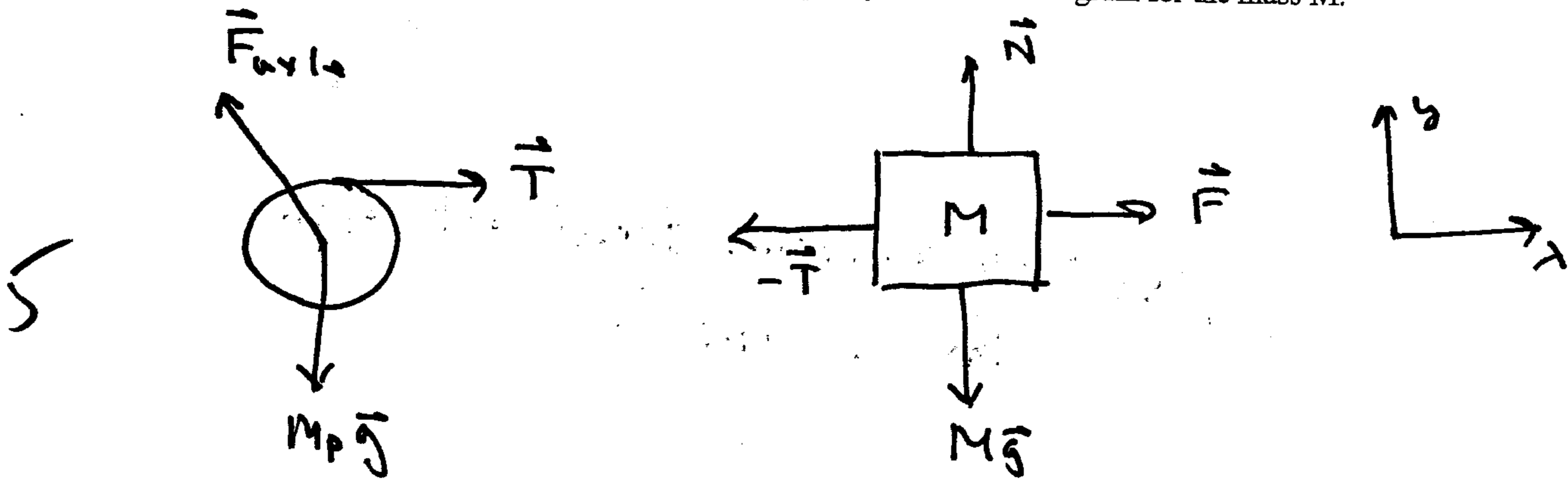
$$= 1.91 \times 10^4 \text{ rev}$$

✓

1) (15 pts) The picture below shows a pulley mounted on a frictionless axis. The pulley has moment of inertia I , radius R , and mass M_p . A "physics string" is wrapped around the pulley and is attached to a block of mass M that slides on a horizontal frictionless surface. A horizontal force of magnitude F is applied to the block as shown. Assume that there is no slipping between the string and the pulley.



a) In the space provided, draw a force diagram for the pulley and a force diagram for the mass M .



b) Derive a formula for the acceleration of the mass M . The only symbols that should appear in your formula are the symbols on the diagram along with numerical factors like the number 2.

$$F - T = Ma \quad T = I\alpha$$

$$I\alpha = RT \quad \alpha = \frac{a}{R} \Rightarrow \frac{Ia}{R^2} = T$$

$$\frac{Ia}{R^2} = F - Ma$$

$$a = \frac{F}{M + I/R^2}$$

c) Drive a formula that gives the total torque acting on the pulley. Torque is a vector. Give the direction of the torque. The only symbols that should appear in your formula are the symbols on the diagram along with numerical factors like the number 2.

$$\hat{T} = I\alpha = \frac{Ia}{R} \quad a = \frac{F}{M + I/R^2}$$

✓

$$\hat{T} = \frac{IF}{R(M + I/R^2)} \quad \otimes$$